
DM420 Two-phase Stepper Motor Driver

Overview

DM420 two-phase hybrid stepper motor drives, DC 12 ~ 36V power supply for the drive voltage 24V ~ 36V, current is less than 2.0A, and the outer diameter of 42 to 57 mm . This drive uses all-digital current loop subdivision control, small torque ripple of the motor, smooth running at low speed, low vibration and noise. When a high-speed can output relatively high torque, high positioning accuracy. Widely used in engraving machines, CNC machine tools, packaging machinery, transmission equipment and other requirements of the higher resolution devices.

Electrical parameters

Input voltage	12-40v input (Peak)
Input current	less than 2A
Outout current	0.44A~2.83A(PEAK)
Power	40W
Temperature	Working temperature:-10~45°C;Storage temperature:-40~70°C
Wet	No condensation and water droplets
Gas	Prohibit combustible gases and conductive dust
Weight	70g

Control signal interface

Figure 1 is a schematic wiring drive

1, the control signal definition

PUL: pulse signal input terminal

DIR: stepping direction signal input

+5 V: signal input terminal of the sun

ENBL: Offline enable signal input

Offline enable signal is reset when a valid drive failure, prohibit any valid pulse, the output power of the drive element is closed, no motor holding torque.

2, the control signals connection

PC control signal can be active high, you can also active low. When active high, put all the negative terminal of the control signal as the signal ground together, when active low, put all the positive terminal of the control signals together as a signal common terminal. Now give an example of open collector output and PNP , the interface circuit diagram is as follows:

集电极开路（共阳极）

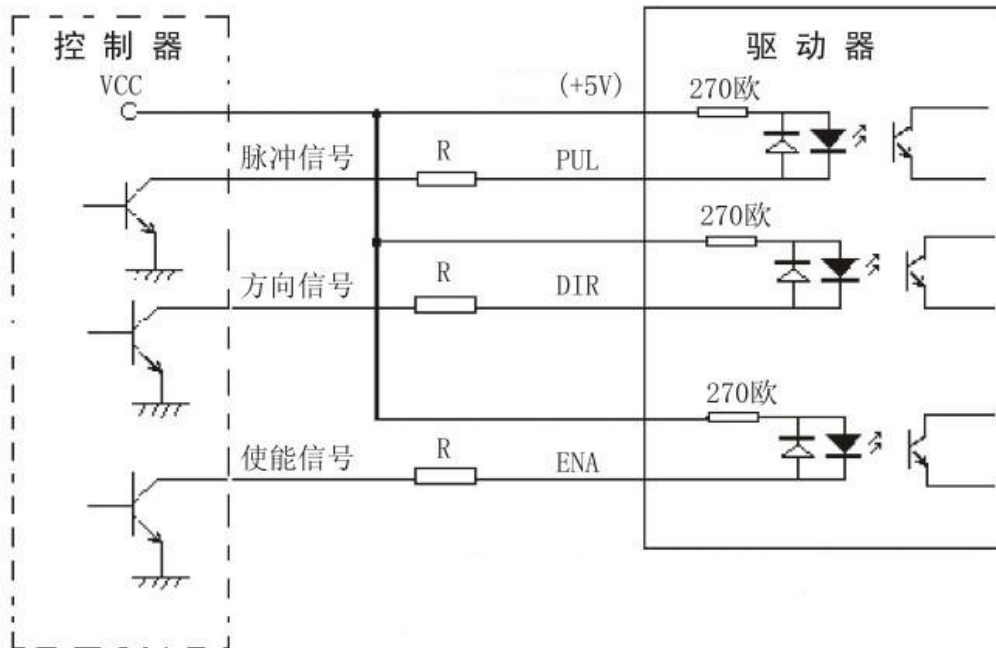


Figure 1. Input interface circuit (common anode connection)
Controller Open collector output

PNP输出

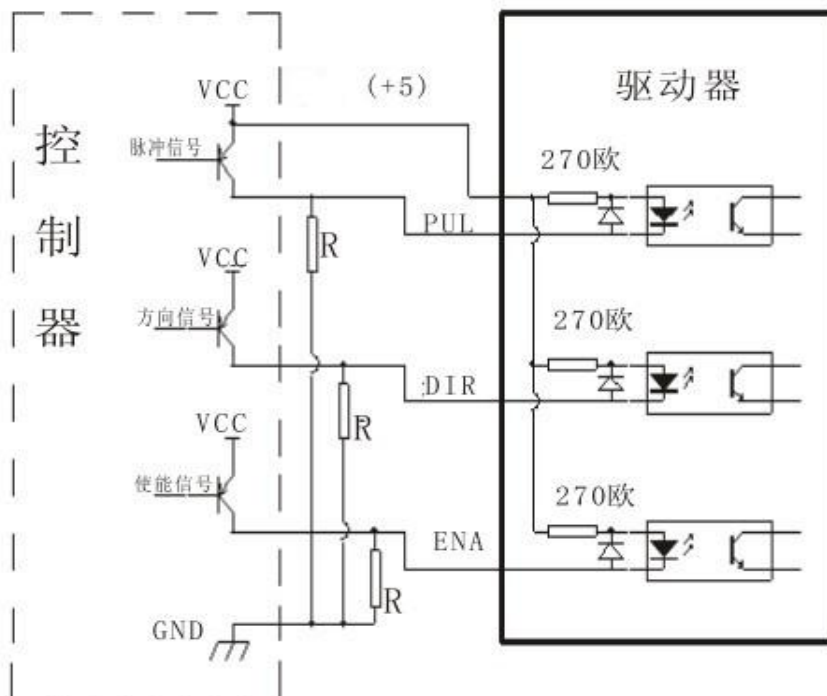


Figure 2. Input interface circuit (common cathode connection)
Controller PNP output

Note: VCC is 5V, R is short;
VCC is 12V, R is 1K, 1/8W greater resistance;
VCC is 24V, R is 2K, more than 1/8W resistor
R must be connected to the controller signals

Functions (implemented by DIP switches on the drive panel)

1, set the number of steps per motor revolution
Drive motor may be a few steps per revolution are set to 200, 400, 800, 1600, 3200, 6400, 12800, 25600 step. Users can drive through the front panel DIP switch SW5, SW6, SW7 bit to set the drive number (Pulse / rev) as shown in Table 1 step:

SW5condition	ON	OFF	ON	OFF	ON	OFF	ON	OFF
SW6condition	ON	ON	OFF	OFF	ON	ON	OFF	OFF
SW7condition	ON	ON	ON	ON	OFF	OFF	OFF	OFF
Pulse/rev	200	400	800	1600	3200	6400	12800	25600
Micro	1	2	4	8	16	32	64	128

Table 1

2, the control mode selection
DIP switch SW4 bit can be set to two control modes:
When set to "OFF", the semi-streaming capabilities to none.
When set to "ON", in order to have a semi-streaming capabilities.
Semi-flow function means no step pulse 500ms, the driver output current is automatically reduced to 70% of rated output current is used to prevent motor heat.

3, set the output phase current
In order to drive different torque stepper motors, the user can switch SW1 on the drive panel, SW2, SW3 bit to set the drive's output phase current (RMS) amperes, each switch position corresponding output current, different models drive different values of the corresponding output current. Detailed in Table 2.

SW1	SW2	SW3	PEAK	RMS
ON	ON	ON	0.44 A	0.31 A
OFF	ON	ON	0.62 A	0.44 A
ON	OFF	ON	0.74 A	0.52 A
OFF	OFF	ON	0.86 A	0.61 A
ON	ON	OFF	1.46 A	1.03 A

OFF	ON	OFF	1.69 A	1.20 A
ON	OFF	OFF	2.14 A	1.51 A
OFF	OFF	OFF	2.83 A	2.00 A

Table2

Power Interface

1, DC +, DC-: drive power connector

DC +: positive level DC power supply voltage DC 12 ~ 36V. The maximum current is 2A.

DC-: negative DC power level.

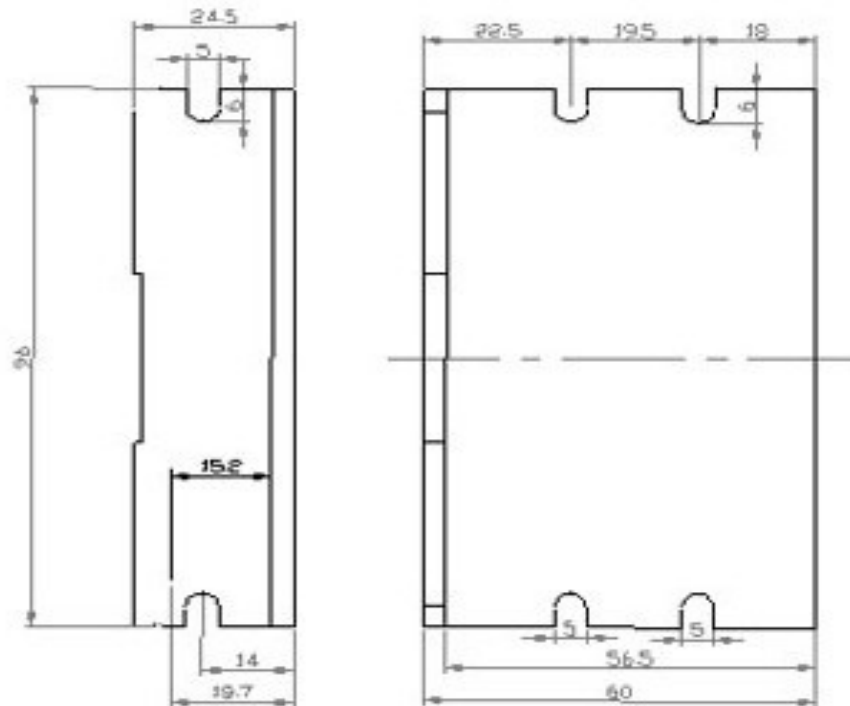
2, A + A-B + B-: connect the two-phase hybrid stepping motor

Connect the drive and two-phase hybrid stepping motors using four-wire system, the motor windings in parallel and series connection, parallel connection, high-speed performance, but the drive current is large (1.73 times the motor winding current),

When connected in series with the drive current is equal to the motor winding currents.

Installation

Have 20mm of space around, can not be placed next to other heating equipment, to avoid dust, oil mist, corrosive gas, too much humidity and strong vibration. +



Trouble shooting

1、Status lights indicate

PWR: green light, work light.

PWR: When out the lights, the fault is off, the motor phase short circuit, overvoltage and under voltage protection.

2、Trouble and Eliminate

Trouble	Reason	Solution
LED is not lit	Pick the wrong power	Check the power connection
	Low power supply voltage	Improve the supply voltage
Motor does not turn, and no holding torque	Wrong motor connection	Correct motor connections
	Offline enable RESET signal is active	Make RESET invalid
Motor does not turn, but holding torque	No pulse signal input	Pulse width and level adjustment signal
Motor rotates in the wrong direction	Power line phase sequence is wrong	Swap any two connected lines
	Wrong direction signal input	Change direction setting
Motor torque is too small	Phase current is too small	set Phase current correctly
	Too fast acceleration	Reduce the acceleration values
	Motor stall	Ruled out mechanical failure
	The drive does not match the motor	Change the appropriate drive

Drive wiring

A complete stepper motor control system should contain stepper drives, DC power supply and controller (pulse source). The following is a typical system wiring diagram:

